

# MRU 5



KONGSBERG



## The ideal marine motion sensor

This 5<sup>th</sup> generation MRU 5 is specially designed for high precision motion measurements in marine application and for users requiring high accuracy roll, pitch and heave measurements.

### Typical applications

The MRU 5 is the ideal sensor for motion compensation of multi-beam echo sounders, offshore cranes, hydroacoustic positioning systems and dynamic motion monitoring of roll, pitch and linear accelerations on offshore structures. The MRU 5 provides documented roll and pitch dynamic accuracy of 0.005° 1-sigma at a ±5° amplitude. The unit maintains its specified accuracy aboard any surface vessel or subsea vehicle.

### Function

The MRU 5 product is updated with the most sophisticated MEMS gyro available, the mMRG03 (milli Mru Rate Gyro). The mMRG03 is developed and manufactured by Kongsberg Discovery AS. The MRG gyro combines low noise, excellent bias stability and gain accuracy. Very high reliability is achieved by using solid-state sensors with no rotational or mechanical wear-out parts.

The unit is delivered with Windows based configuration and data presentation software. In this software vector arms from where the MRU is mounted to the center of gravity (CG) and two individually configurable monitoring points (MPs), can be defined. The heave measurements can be output in four different locations (the MRU itself, CG, MP1 and MP2) simultaneously on serial lines or Ethernet port. A typical monitoring point is the transducer head or the crane tip.

### Output variables

The MRU 5 outputs roll, pitch and yaw angles and corresponding angular rate vectors. The unit outputs relative (dynamic) heave, surge and sway positions, velocities and accelerations in adjustable frames.

### PFreeHeave® algorithm

The PFreeHeave algorithm uses past measurements to output a correct and phase-free heave from the MRU. PFreeHeave has an advantage in long swell conditions and for applications that can utilize a heave signal that is delayed some minutes, typically seabed mapping applications.

### External inputs

The MRU 5 accepts input of external speed and heading information on separate serial lines or Ethernet for improved accuracy in heave, roll and pitch during turns and accelerations. For time synchronization the MRU accepts a 1-second time pulse (1PPS) input on a TTL line (XIN) or as RS-232/422 signal.

### Digital I/O protocols

For this 5<sup>th</sup> generation MRU data is available through both Ethernet interface and serial lines enabling easy distribution of MRU data to multiple users on board the vessel. Output protocols for commonly used survey equipment are available on two individually configurable serial lines and Ethernet/UDP.

## FEATURES

- 0.005° roll and pitch accuracy
- Exceptionally low angle noise and bias stability
- Outputs on RS-232, RS-422 and Ethernet
- High output data rate (200 Hz)
- Precise heave at long wave periods by use of PFreeHeave® algorithms
- Lever arm compensation to two individually configurable monitoring points
- Small size, light weight and low power consumption
- No limitation to mounting orientation
- Each MRU delivered with Calibration Certificate
- Selectable communication protocols in the Windows based MRU configuration software
- 2-year warranty



## Technical specifications

### MRU 5

#### Orientation output

Angular orientation range	±45°
Resolution in all axes	0.0001°
Static accuracy roll & pitch <sup>1)</sup>	0.02° RMS
Dynamic accuracy roll & pitch <sup>2)</sup> , (for a ±5° amplitude)	0.005 1-sigma
Bandwidth	0 - 10 Hz

#### Gyro output

Angular rate range	±75°/s
Angular rate noise	0.010°/s RMS
Scale factor error	0.02 % RMS

#### Acceleration output

Acceleration range (all axes)	±45 m/s <sup>2</sup>
Acceleration noise	0.002 m/s <sup>2</sup> RMS
Scale factor error	0.02% RMS

#### Heave output

Output range	±50 m, adjustable
Heave accuracy for 0 to 25 s motion periods (real-time)	5 cm or 5% whichever is highest (RMS)
Heave accuracy for 10 s motion period (real-time)	1 cm or 1% whichever is highest (RMS)
Heave accuracy for 0 to 50 s motion periods (delayed)	1 cm or 1% whichever is highest (RMS)
Heave velocity accuracy	0.01 m/s RMS
Bandwidth	0.04 - 10 Hz

#### Electrical

Voltage input	10 - 36 V DC
Power consumption	Max 8 W
Serial ports:	
• COM1	Bidirectional RS-422
• COM2	Bidirectional RS-422 from junction box, user configurable RS-232, RS-422
• COM3 & COM4	Input only, user configurable RS-232, RS-422

Analog channels (junction box) # 4, ±10 V, 14 bit resolution

<sup>1</sup> When the MRU is stationary over a 30-minute period.

<sup>2</sup> When the MRU is exposed to a combined two-axis sinusoidal angular motion with 10 minutes duration.

Ethernet output ports	5
Ethernet UPD/IP	10/100 Mbps
Data output rate (max)	200 Hz
Timing	< 1 ms

#### Input formats

NMEA 0183, incl. HDT, HDM, ZDA, VTG, VHW, VBW or MRU Normal format

#### Data output protocols

- MRU normal	- Souder
- NMEA 0183 proprietary	- EM3000
- Atlas Fansweep	- TSS1
- Seapath binary 23, 25, 26	- PFreeHeave®
- PRDID	- KM binary

#### Other data

MTBF (computed)	50000 h
MTBF (service history based)	100000 h
Material	Anodised aluminium
Connector (MIL. spec.)	Souriau 851-36RG 16-26S50

#### Weights and dimensions

Weight	2.2 kg
Dimensions	Ø 105 × 140 mm (4.134 × 5.525")

#### Environmental specifications

Operating temperature	-5 - +55 °C
Storage temperature	-25 - +70 °C
Enclosure protection	IP66
Vibration	IEC 60945/EN 60945

#### Electromagnetic compatibility

Compliance to EMC, immunity/emission	IEC 60945/EN 60945
---	--------------------

Specifications subject to change without any further notice.