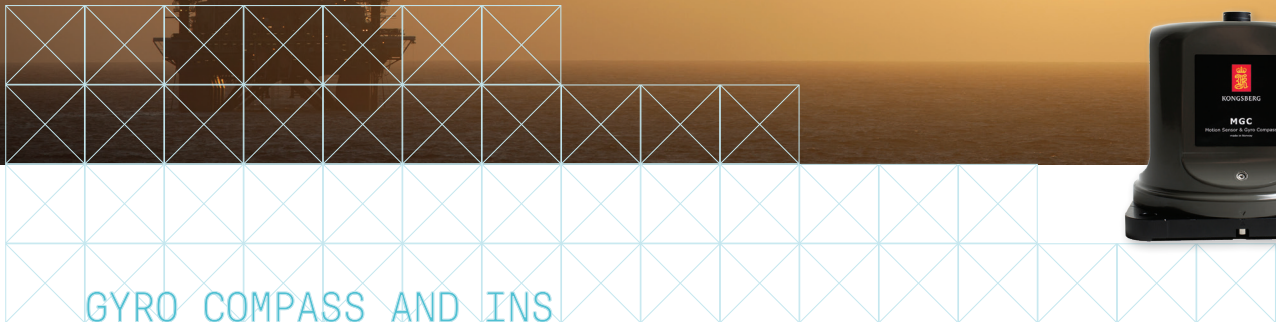


MGC® R5



KONGSBERG



GYRO COMPASS AND INS

A new family of products with motion sensing and gyro compass functionality is introduced. This MGC R5 product, with emphasis on position drift, includes three Ring Laser Gyros and three linear accelerometers.

Typical applications

The MGC R5 product is a fully inertial navigation system (INS). It can output heading, roll, pitch, heave and position. Acceleration and velocity of linear motions, as well as angular rates, are output from the unit. The MGC R5 product outputs both processed and raw (gyro and accelerometer) sensor data.

The MGC R5 can be used as a stand-alone unit or as an IMU in other systems. The product is designed for high precision maritime applications such as offshore operations and seabed mapping.

The product includes integrated navigation algorithms with input from a GNSS receiver for output of aided position and heading data. The proven PFreeHeave® algorithms are part of the navigation algorithms that enable down to 2 cm accuracy in delayed heave output and 3 cm accuracy in real-time heave output. The linear position and velocity measurements can be output in up to four different points on the vessel.

Function

The MGC can operate in Gyrocompass mode and Integrated Navigation mode. In the Gyrocompass mode only, input of speed is required. In this mode the product will output heading, roll, pitch and heave accurately. In the Integrated Navigation mode, input of speed, position and PPS from a GNSS receiver is required (VTG, GGA, ZDA). In this mode the product will output heading, roll, pitch, heave and position. In free inertial mode (GNSS denied environment) the position drift is less

than 20 meters DRMS for a period of 15 minutes (proven performance). The unit is delivered with Windows based configuration and data presentation software, the MRC+. In this software vector arms from where the MGC is mounted to the center of gravity (CG) and two individually configurable monitoring points (MPs) can be defined. The heave measurements can be output in four different locations (the MGC itself, CG, MP1 and MP2) simultaneously on serial lines or Ethernet ports. A typical measurement point is the echo sounder transducer head.

Variables output

The MGC outputs heading, roll and pitch and corresponding angular rate vectors. The unit outputs relative (dynamic) heave position, velocity and acceleration. In the Integrated Navigation mode it also outputs position in north and east direction in addition to height above the ellipsoid.

Digital I/O protocols

MGC data is available through both Ethernet interface and serial lines enabling easy distribution of data to multiple users on board the vessel. Output protocols for commonly used survey equipment are available on two individually configurable serial lines and Ethernet/UDP.

FEATURES

- 0.008° roll and pitch accuracy
- 0.008° secant latitude heading accuracy GNSS aided
- Includes INS capability
- Outputs on RS-232, RS-422 and Ethernet
- High output data rate (200 Hz)
- Precise heave at long wave periods by use of PFreeHeave® algorithms
- Lever arm compensation to two individually configurable monitoring points
- Small size and low power consumption
- Each MGC delivered with a Calibration Certificate
- Selectable communication protocols in the Windows based configuration software



TECHNICAL SPECIFICATIONS

MGC R5

ORIENTATION OUTPUT

Angular orientation range	±180°
Resolution in all axes	0.0001°
Roll, pitch accuracy (unaided)	0.008° RMS
Attitude noise	<0.0003° RMS
Heading accuracy (speed aided)	0.02° RMS sec.lat
Heading accuracy (GNSS aided)	0.008° RMS sec.lat.
Heading settling time to data available	<5 min from start-up
Heading settling time to full accuracy (typical)	8 min from start-up

GYRO OUTPUT

Angular rate range	±125°/s
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ACCELERATION OUTPUT

Acceleration range (all axes)	±45 m/s ²
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HEAVE OUTPUT

Output range	±50 m, adjustable
Periods (real-time)	0 to 30 s
Periods (delayed)	0 to 50 s
Heave accuracy (real-time)	3 cm or 3% whichever is highest
Heave accuracy (delayed)	2 cm or 2% whichever is highest

POSITION OUTPUT

Free inertial drift (GNSS aided)	0.25 nm/h DRMS
Free inertial drift (GNSS aided)	<20 m/15 minutes DRMS

ELECTRICAL

Voltage input	24 V DC nominal (18 to 32 V DC)
Power consumption	Max 12 W (typical 11 W)

Serial ports:

Com1	Bidirectional RS-422
Com2	Bidirectional RS-232
Com3 & Com4	Input only, user configurable RS-232, RS-422
Ethernet output ports	5
Ethernet UPD/IP	10/100 Mbps
Data output rate (max)	200 Hz
Timing	< 1 ms

INPUT FORMATS

NMEA 0183, incl. GGA, VBW, VTG, ZDA or MRU Normal format

OUTPUT FORMATS

- MRU normal	- Sounder
- NMEA 0183 proprietary	- EM3000
- Atlas Fansweep	- TSS1
- Seapath binary 23, 25, 26	- PFreeHeave®
- KM binary	- MDL Trim Cube
- RDI ADCP	- Tokimec PTVG
- NMEA GGA, GLL, HDT, THS, ROT, VTG, GST, VER, HCR	

OTHER DATA

MTBF (computed)	50000 h
MTBF (Service history based)	100000 h
Material	Anodised aluminium
Connector (MIL. spec.)	Souriau 851-36RG 16-26S50

WEIGHTS AND DIMENSIONS

Weight	8.0 kg
Dimensions (HxLxW)	188.9 x 189.5 x 189.5 mm

ENVIRONMENTAL SPECIFICATIONS

Operational temperature range	-15 °C to +55 °C
Storage temperature range	-25 °C to +70 °C
Vibration	IEC 60945/EN 60945
Enclosure protection	IP66

Specifications subject to change without any further notice.

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