

The roll and pitch motion sensor

This 5th generation roll and pitch motion sensor is specially designed for use in marine applications and is the ideal sensor for roll and pitch measurements on board ships.

Typical applications

The MRU D is specially designed for roll and pitch measurements within voyage recording, dynamic positioning systems, fishing sonars and telecommunication antenna system.

This unit has to be mounted in a fixed direction relative to the vessel and is best suited for applications with limited range in roll and pitch. If unlimited mounting orientation and/or unlimited mounting range is required, we recommend one of the MRU models with sensors in all three axis. The MRU D has to be mounted with the connector pointing up or down.

Function

The unit is delivered with a Windows based configuration and data presentation software. By configuring the unit with the vector between the MRU and the vessel Center of Gravity (CG), the MRU D will output accurate roll and pitch measurements even when it is mounted high up in the vessel, like on the bridge. This is due to the capability to suppress the effect of horizontal acceleration on the roll and pitch performance. This makes the unit superior to inclinometers, pendulous devices and standard Vertical Reference Units.

Each MRU D unit is delivered with a Calibration Certificate stating that the unit is tested and found within the specifications.

Variables output

The MRU D outputs roll and pitch angles and corresponding angular rate vectors fixed to the vehicle frame. In addition, the unit can output surge and sway accelerations.

Digital I/O protocols

MRU data is available through both serial lines and Ethernet interface enabling easy distribution of MRU data to multiple users on board the vessel. Output data are available on two individually configurable serial lines and Ethernet/UDP. Output variables are transmitted as IEEE 32-bit floats (recommended) or as scaled integers. In addition, ASCII-based NMEA 0183 proprietary sentences can be selected as data output protocols.





FEATURES

- 0.15° roll and pitch dynamic accuracy
- Outputs real-time roll and pitch
 measurements
- Suppression of horizontal acceleration when mounted off the vessel Center of Gravity (CG)
- Outputs on RS-232, RS-422 and Ethernet
- High output data rate (200 Hz)
- High reliability and no scheduled maintenance, no mechanical wearout parts
- Small size, light weight and low power consumption
- Each MRU delivered with Calibration Certificate
- Selectable communication protocols in the Windows based MRU configuration software
- Export license not required
- 2-year warranty



Technical specifications

±25°

0.0001°

±75°/s

0.2° RMS

0.15 1-sigma

0.03°/s RMS

0.01 m/s² RMS

0.05% RMS

10 - 36 V DC

0.3 % RMS

MRU D

Roll and pitch output

Angular orientation range Resolution roll & pitch Static accuracy¹⁾ Dynamic accuracy²⁾ (for a ±5° amplitude)

Gyro output

Angular rate range Angular rate noise Scale factor error

Surge and sway acceleration output ±160 m/s²

Acceleration range Acceleration noise Scale factor error

Electrical

Voltage input Power consumption Serial ports: COM1

COM₂

COM3 & COM4

Input serial line Ethernet output ports

Ethernet UPD/IP

Timina

Data output rate (max)

Max 3 W Bidirectional RS-422 Bidirectional RS-422 from junction box, user configurable RS-232, RS-422 Input only, user configurable RS-232, RS-422 Analog channels (junction box)# 4, ±10 V, 14 bit resolution Two RS-232 or two RS-422 5

Other data

MTBF (computed) MTBF (service history based) Material Connector (MIL. spec.)

50000 h 100000 h Anodised aluminium Souriau 851-36RG 16-26S50

Weights and dimensions

Weight Dimensions 1.9 kg Ø 105 × 140 mm (4.134 × 5.525")

Environmental specifications

Operating temperature Storage temperature Enclosure protection Vibration

-5 - +55 °C -25 - +70 °C IP66 IEC 60945/EN 60945

Electromagnetic compatibility

Compliance to EMC, immunity/emission

IEC 60945/EN 60945

When the MRU is stationary over a 30-minute period. 1

2 When the MRU is exposed to a combined two-axis sinusoidal angular motion with 10 minutes duration.

10/100 Mbps

200 Hz

 $< 1 \, \text{ms}$