MRU H

The versatile heave compensator

This 5th generation MRU is specially designed for heave compensation applications.

Typical applications
The MRU H is specially designed for motion measurements in marine applications requiring highly accurate heave measurements in environments with extreme horizontal accelerations. This MRU is an ideal sensor for roll, pitch and heave compensation of offshore cranes and echo sounders. The MRU H can also be used for typical ship motion monitoring applications such as helideck motion monitoring, hydroacoustic positioning systems, as well as hull stress monitoring.

Function
The MRU H incorporates three highly accurate accelerometers and three Micro-Electro-Mechanical-Structures (MEMS) angular rate gyros. This unit achieves high reliability by using solid-state sensors with no rotational or mechanical wear-out parts.

The unit is delivered with Windows based configuration and data presentation software. In this software vector arms from where the MRU is mounted to center of gravity (CG) and two individually configurable monitoring points (MPs), can be defined. The heave measurements can be output in four different locations (the MRU itself, CG, MP1 and MP2) simultaneously on serial lines or Ethernet port. A typical monitoring point is the transducer head or the crane tip.

Output variables
The MRU H outputs roll, pitch and heave together with linear acceleration in 3-axes. The MRU H outputs heave position, velocity and accelerations in adjustable frames. In addition, roll and pitch angles and corresponding angular rate vectors are output.

PFreeHeave® algorithm
The PFreeHeave algorithm uses past measurements to output a correct and phase-free heave from the MRU. PFreeHeave has an advantage in long swell conditions and for applications that can utilize a heave signal that is delayed some minutes, typically seabed mapping applications.

External inputs
The MRU H accepts input of external speed and heading information on separate serial lines or Ethernet for improved accuracy in heave, roll and pitch during turns and accelerations. For time synchronization the MRU accepts a 1-second time pulse (1PPS) input on a TTL line (XIN) or as RS-232/422 signal.

Digital I/O protocols
For this 5th generation MRU data is available through both Ethernet interface and serial lines enabling easy distribution of MRU data to multiple users on board the vessel. Output protocols for commonly used survey equipment are available on two individually configurable serial lines and Ethernet/UDP.

FEATURES

- 0.010° roll and pitch dynamic accuracy
- High accuracy heave measurements even in dynamic environments
- Outputs on RS-232, RS-422 and Ethernet
- High output data rate (200 Hz)
- Precise heave at long wave periods by use of PFreeHeave® algorithms
- Lever arm compensation to two individually configurable monitoring points
- Small size, light weight and low power consumption
- No limitation to mounting orientation
- Each MRU delivered with Calibration Certificate
- Selectable communication protocols in the Windows based MRU configuration software
- 2-year warranty

Technical specifications

MRU H

Orientation output
Angular orientation range	±180°
Resolution in all axes	0.0001°
Static accuracy roll & pitch[1]	0.03° RMS
Dynamic accuracy roll & pitch[2], (for a ±5° amplitude)	0.010 1-sigma

Gyro output
Angular rate range	±150°/s
Angular rate noise	0.015°/s RMS
Scale factor error	0.08 % RMS

Acceleration output
Acceleration range (all axes)	±45 m/s²
Acceleration noise	0.002 m/s² RMS
Scale factor error	0.02% RMS

Heave output
Output range	±50 m, adjustable
Heave accuracy for 0 to 25 s motion periods (real-time)	5 cm or 5% whichever is highest (RMS)
Heave accuracy for 10 s motion period (real-time)	1 cm or 1% whichever is highest (RMS)
Heave accuracy for 0 to 50 s motion periods (delayed)	1 cm or 1% whichever is highest (RMS)
Heave velocity accuracy	0.01 m/s RMS

Electrical
Voltage input	10 - 36 V DC
Power consumption	Max 8 W (typical 7.2 W)
Serial ports:	
• COM1	Bidirectional RS-422
• COM2	Bidirectional RS-422 from junction box, user configurable RS-232, RS-422
• COM3 & COM4	Input only, user configurable RS-232, RS-422
Analog channels (junction box)	# 4, ±10 V, 14 bit resolution
Ethernet output ports	5

1 When the MRU is stationary over a 30-minute period.
2 When the MRU is exposed to a combined two-axis sinusoidal angular motion with 10 minutes duration.

Ethernet UPD/IP	10/100 Mbps
Data output rate (max)	200 Hz
Timing	< 1 ms

Input formats
NMEA 0183, incl. HDT, HDM, ZDA, VTG, VHW, VBW or MRU Normal format

Data output protocols
- MRU normal	- Sounder
- NMEA 0183 proprietary	- EM3000
- Atlas Fansweep	- TSS1
- Seapath binary 23, 25, 26	- PFreeHeave®
- PRDID	- KM binary

Other data
MTBF (computed)	50000 h
MTBF (service history based)	100000 h
Material	Anodised aluminium
Connector (MIL. spec.)	Souriau 851-36RG 16-26S50

Weights and dimensions
Weight	2.2 kg
Dimensions	Ø 105 × 140 mm (4.134 × 5.525")

Environmental specifications
Operating temperature	-5 - +55 °C
Storage temperature	-25 - +70 °C
Enclosure protection	IP66
Vibration	IEC 60945/EN 60945

Electromagnetic compatibility
Compliance to EMC, immunity/emission	IEC 60945/EN 60945

Specifications subject to change without any further notice.